

Autonomous

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"When anything can be owned, how can we be free? Earth, 2144. Jack is an anti-patent scientist turned drug pirate, a pharmaceutical Robin Hood traversing the world in a submarine, fabricating cheap scrips for poor people who can't otherwise afford them. But her latest drug hack leaves a trail of lethal overdoses as people become addicted to their work, repeating job tasks until they become insane. Hot on her trail, an unlikely pair: Elias, a brooding military agent, and his partner, Paladin, a young indentured robot. As they race to stop information about the hacked drugs at their source, they form an uncommonly close relationship that neither of them fully understands, and Paladin begins to question their connection - and a society that profits from indentured robots" --

Autonomous Robots

An introduction to the science and practice of autonomous robots that reviews over 300 current systems and examines the underlying technology.

Designing Autonomous AI

Early rules-based artificial intelligence demonstrated intriguing decision-making capabilities but lacked perception and didn't learn. AI today, primed with machine learning perception and deep reinforcement learning capabilities, can perform superhuman decision-making for specific tasks. This book shows you how to combine the practicality of early AI with deep learning capabilities and industrial control technologies to make robust decisions in the real world. Using concrete examples, minimal theory, and a proven architectural framework, author Kence Anderson demonstrates how to teach autonomous AI explicit skills and strategies. You'll learn when and how to use and combine various AI architecture design patterns, as well as how to design advanced AI without needing to manipulate neural networks or machine learning algorithms. Students, process operators, data scientists, machine learning algorithm experts, and engineers who own and manage industrial processes can use the methodology in this book to design autonomous AI. This book examines: Differences between and limitations of automated, autonomous, and human decision-making Unique advantages of autonomous AI for real-time decision-making, with use cases How to design an autonomous AI from modular components and document your designs

Introduction to Autonomous Mobile Robots, second edition

The second edition of a comprehensive introduction to all aspects of mobile robotics, from algorithms to mechanisms. Mobile robots range from the Mars Pathfinder mission's teleoperated Sojourner to the cleaning robots in the Paris Metro. This text offers students and other interested readers an introduction to the fundamentals of mobile robotics, spanning the mechanical, motor, sensory, perceptual, and cognitive layers the field comprises. The text focuses on mobility itself, offering an overview of the mechanisms that allow a mobile robot to move through a real world environment to perform its tasks, including locomotion, sensing, localization, and motion planning. It synthesizes material from such fields as kinematics, control theory, signal analysis, computer vision, information theory, artificial intelligence, and probability theory. The book presents the techniques and technology that enable mobility in a series of interacting modules. Each chapter treats a different aspect of mobility, as the book moves from low-level to high-level details. It covers all aspects of mobile robotics, including software and hardware design considerations, related technologies, and algorithmic techniques. This second edition has been revised and updated throughout, with 130 pages of new

material on such topics as locomotion, perception, localization, and planning and navigation. Problem sets have been added at the end of each chapter. Bringing together all aspects of mobile robotics into one volume, *Introduction to Autonomous Mobile Robots* can serve as a textbook or a working tool for beginning practitioners. Curriculum developed by Dr. Robert King, Colorado School of Mines, and Dr. James Conrad, University of North Carolina-Charlotte, to accompany the National Instruments LabVIEW Robotics Starter Kit, are available. Included are 13 (6 by Dr. King and 7 by Dr. Conrad) laboratory exercises for using the LabVIEW Robotics Starter Kit to teach mobile robotics concepts.

Autonomous Flying Robots

The advance in robotics has boosted the application of autonomous vehicles to perform tedious and risky tasks or to be cost-effective substitutes for their - man counterparts. Based on their working environment, a rough classification of the autonomous vehicles would include unmanned aerial vehicles (UAVs), - manned ground vehicles (UGVs), autonomous underwater vehicles (AUVs), and autonomous surface vehicles (ASVs). UAVs, UGVs, AUVs, and ASVs are called UVs (unmanned vehicles) nowadays. In recent decades, the development of - manned autonomous vehicles have been of great interest, and different kinds of autonomous vehicles have been studied and developed all over the world. In particular, UAVs have many applications in emergency situations; humans often cannot come close to a dangerous natural disaster such as an earthquake, a flood, an active volcano, or a nuclear disaster. Since the development of the first UAVs, research efforts have been focused on military applications. Recently, however, demand has arisen for UAVs such as aero-robots and flying robots that can be used in emergency situations and in industrial applications. Among the wide variety of UAVs that have been developed, small-scale HUAVs (helicopter-based UAVs) have the ability to take off and land vertically as well as the ability to cruise in flight, but their most important capability is hovering. Hovering at a point enables us to make more effective observations of a target. Furthermore, small-scale HUAVs offer the advantages of low cost and easy operation.

Autonomous

William Mackler is about to go on the road trip of a lifetime. After winning a contest—and nearly dying in the process—he becomes the proud owner of *Autonomous*, a driverless car that knows where you want to go before you do. #Worthit! To sweeten the deal he gets to pick three friends to go with him on a cross-country trip. For William, a reckless adrenaline junkie, this is the perfect last hurrah before he and his friends go their separate ways after graduation. But *Autonomous* is more than just a car without a steering wheel. It's capable of downloading all of the passengers' digital history—from the good, to the bad, to the humiliating. The information is customized into an itinerary that will expose a few well-kept secrets, but it will also force William to face some inner demons of his own. Think you know *Autonomous*? The real question is, how much does *Autonomous* know about you? This funny, tense, action-packed thriller combines topical social-media-privacy stakes with jaw-dropping high-tech action for a road trip saga like no other.

The Book in Movement

Over the past two decades, Latin America has seen an explosion of experiments with autonomy, as people across the continent express their refusal to be absorbed by the logic and order of neoliberalism. The autonomous movements of the twenty-first century are marked by an unprecedented degree of interconnection, through their use of digital tools and their insistence on the importance of producing knowledge about their practices through strategies of self-representation and grassroots theorization. *The Book in Movement* explores the reinvention of a specific form of media: the print book. Magalí Rabasa travels through the political and literary underground of cities in Mexico, Bolivia, Argentina, and Chile to explore the ways that autonomous politics are enacted in the production and circulation of books.

Intelligent Autonomous Systems

This research book contains a sample of most recent research in the area of intelligent autonomous systems. The contributions include: General aspects of intelligent autonomous systems Design of intelligent autonomous robots Biped robots Robot for stair-case navigation Ensemble learning for multi-source information fusion Intelligent autonomous systems in psychiatry Condition monitoring of internal combustion engine Security management of an enterprise network High dimensional neural nets and applications This book is directed to engineers, scientists, professor and the undergraduate/postgraduate students who wish to explore this field further.

Autonomous Systems and Intelligent Agents in Power System Control and Operation

Autonomous systems are one of the most important trends for the next generation of control systems. This book is the first to transfer autonomous systems concepts and intelligent agents theory into the control and operation environment of power systems. The focus of this book is to design a future control system architecture for electrical power systems, which copes with the changed requirements concerning complexity and flexibility and includes several applications for power systems. This book draws the whole circle from the theoretical and IT-concept of autonomous systems for power system control over the required knowledge-based methods and their capabilities to concrete applications within this field.

Autonomous Robots Research Advances

Autonomous robots are robots which can perform desired tasks in unstructured environments without continuous human guidance. Many kinds of robots have some degree of autonomy. Different robots can be autonomous in different ways. A high degree of autonomy is particularly desirable in fields such as space exploration, where communication delays and interruptions are unavoidable. Some modern factory robots are \"autonomous\" within the strict confines of their direct environment. The exact orientation and position of the next object of work and (in the more advanced factories) even the type of object and the required task must be determined. This can vary unpredictably (at least from the robot's point of view). One important area of robotics research is to enable the robot to cope with its environment whether this be on land, underwater, in the air, underground, or in space. This book presents the latest research from around the globe.

Autonomous Learner Model Resource Book

Autonomous Learner Model Resource Book includes activities and strategies to support the development of autonomous learners. More than 40 activities are included, all geared to the emotional, social, cognitive, and physical development of students. Teachers may use these activities and strategies with the entire class, small groups, or with individuals who are ready to be independent, self-directed, lifelong learners. These learners have the passions, abilities, skills, and attitudes to go beyond the regular curriculum and take control of their own educational pathways. Field-tested strategies and activities in the book include Find Someone Who, Teacher and Learner Questionnaires, Lifelong Notebook, Time Capsule, and Night of the Notables.

Autonomous Mobile Robots

This book explores a new rapidly developing area of robotics. It describes the state of the art in intelligence control, applied machine intelligence, and research and initial stages of manufacturing autonomous mobile robots. A complete account of the theoretical and experimental results obtained during the last two decades together with some generalizations on Autonomous Mobile Systems are included in this book.

The Autonomous Revolution

The bestselling authors of The Virtual Corporation describe how the rise of AI and virtual environments are ushering in an epic cultural transformation. We are at the dawn of the Autonomous Revolution, a turning

point in human history as decisive as the Agricultural and Industrial Revolutions. More and more, AI-based machines are replacing human beings, and online environments are gathering our data and using it to manipulate us. This loss of human autonomy amounts to nothing less than a societal phase change, a fundamental paradigm shift. The same institutions will remain—schools, banks, churches, and corporations—but they will radically change form, obey new rules, and use new tools. William H. Davidow and Michael S. Malone go deeply into the enormous implications of these developments. They show why increases in productivity no longer translate into increases in the GDP and how zero cost, one-to-many communications have been turned into tools for cybercrime and propaganda. Many of the book's recommendations—such as using taxes to control irresponsible internet behavior and enabling people to put their data into what are essentially virtual personal information “safety deposit boxes”—are bold and visionary, but we must figure out how we will deal with these emerging challenges now, before the Autonomous Revolution overcomes us. “Lots of books talk about what's happening. This book talks about the why behind the what. It will transform your view of the future.” —Geoffrey Moore, bestselling author of *Crossing the Chasm* “A provocative work combining historical inquiry, present-day technology crises, and possible future solutions.”—Library Journal

Building Autonomous Learners

This edited work presents a collection of papers on motivation research in education around the globe. Pursuing a uniquely international approach, it also features selected research studies conducted in Singapore under the auspices of the Motivation in Educational Research Lab, National Institute of Education, Singapore. A total of 15 chapters include some of the latest findings on theory and practical applications alike, prepared by internationally respected researchers in the field of motivation research in education. Each author provides his/her perspective and practical strategies on how to maximize motivation in the classroom. Individual chapters focus on theoretical and practical considerations, parental involvement, teachers' motivation, ways to create a self-motivating classroom, use of ICT, and nurturing a passion for learning. The book will appeal to several different audiences: firstly, policymakers in education, school leaders and teachers will find it a valuable resource. Secondly, it offers a helpful guide for researchers and teacher educators in pre-service and postgraduate teacher education programmes. And thirdly, parents who want to help their children pursue lifelong learning will benefit from reading this book.

Autonomous Learning in the Workplace

Traditionally, organizations and researchers have focused on learning that occurs through formal training and development programs. However, the realities of today's workplace suggest that it is difficult, if not impossible, for organizations to rely mainly on formal programs for developing human capital. This volume offers a broad-based treatment of autonomous learning to advance our understanding of learner-driven approaches and how organizations can support them. Contributors in industrial/organizational psychology, management, education, and entrepreneurship bring theoretical perspectives to help us understand autonomous learning and its consequences for individuals and organizations. Chapters consider informal learning, self-directed learning, learning from job challenges, mentoring, Massive Open Online Courses (MOOCs), organizational communities of practice, self-regulation, the role of feedback and errors, and how to capture value from autonomous learning. This book will appeal to scholars, researchers, and practitioners in psychology, management, training and development, and educational psychology.

Autonomous Vehicles - Applications and Perspectives

In recent times, remarkable progress has taken place in the field of autonomous vehicles, reshaping industries such as logistics, transportation, defense, and more. The quest for achieving fully autonomous systems has been a thrilling yet demanding journey, as researchers and engineers continually push the limits of technological ingenuity. *Autonomous Vehicles - Applications and Perspectives* delves into the field of autonomous vehicles across eight chapters that cover various facets of this domain. The book is organized

into four sections: \"Introduction\

Deception in Autonomous Transport Systems

This book provides a comprehensive overview of deception in autonomous transport systems. This involves investigating the threats facing autonomous transport systems and how they can contribute towards a deceptive attack, followed by their potential impact if successful, and finally, how they can be mitigated. The work in this book is grouped into three parts. This first part focuses on the area of smart cities, policies, and ethics. This includes critically appraising the trade-off between functionality and security with connected and autonomous vehicles. The second discusses a range of AI applications in the wider field of smart transport and mobility, such as detecting anomalies in vehicle behaviour to investigating detecting disobedient vehicles. Finally, the third part presents and discusses cybersecurity-related aspects to consider when dealing with Connected and Autonomous Vehicles (CAVs) and smart urban infrastructure. This includes analysing different attacks to investigating secure communication technologies. CAVs are a game-changing technology with the potential to transform the way transport is perceived, mobility is serviced, travel ecosystems 'behave', and cities and societies as a whole function. There are many foreseen safety, accessibility and sustainability benefits resulting from the adoption of CAVs because of their ability, in theory, to operate error-free and collaboratively, ranging from accident prevention, congestion reduction and decreased carbon emissions to time savings, increased social inclusion, optimised routing, and better traffic control. However, no matter what the expected benefits are, CAVs are at the same time susceptible to an unprecedented number of new digital and physical threats. The severity of these threats has resulted in an increased effort to deepen our understanding of CAVs when it comes to their safety and resilience. In this complex and multi-faceted scenario, this book aims to provide an extensive overview of the risks related to the malicious exploitation of CAVs and beyond, the potential ways in which vulnerabilities can be exploited, prevention and mitigation policies and techniques, and the impact that the non-acceptance of Connected and Autonomous Mobility can have on the Smart City agenda. This book targets researchers, practitioners, and advanced-level students in computer science and transport engineering.

The Legal Adaptation Power in China's Ethnic Autonomous Areas

The book provides a comprehensive analysis of legal adaptation mechanisms within ethnically diverse regions. This scholarly work examines how legal systems are modified to accommodate the unique cultural, social and historical contexts of ethnic autonomous areas while maintaining national legal cohesion. The book explores the theoretical foundations of legal adaptation power, analyzing its constitutional principles including regional ethnic autonomy, ethnic equality and popular sovereignty. It traces the historical evolution of legal adaptation in China and examines current practices across various domains including civil code, criminal law, electoral law and family planning regulations. The authors identify several challenges in implementing legal adaptation, including geographical imbalances, inconsistent application and institutional deficiencies. They propose a framework for improvement focused on strengthening legislative awareness, enhancing professional quality and establishing effective accountability mechanisms. The work makes a significant contribution by emphasizing how legal adaptations help guarantee equal rights for ethnic minorities, resolve conflicts between national policies and local customs, and promote economic and social development. It advocates for a balanced approach that respects ethnic characteristics while maintaining the principle of national legal uniformity, ultimately supporting a more responsive and inclusive legal system in ethnic autonomous regions.

Human-Centred Autonomous Shipping

Tracing the development of autonomous and automated shipping from a hype of unmanned ships to a more realistic use of automation to augment humans in maritime operations, this book shows why human factors and human-centred design are essential to the endeavour. Themes addressed in the book include technology and cybersecurity, regulation and classification, and competence and skills. It combines commentary and

insight from experts across the industry as well as academia and describes a roller-coaster ride from conceptual idea via a period of hype where technologists and engineers enthusiastically advocated a rapid development as many others in the maritime industry felt compelled, but struggled, to follow and finally to a more measured view as cumulative experience started to show the limitations, risks, and the lack of a generic business case. This book is intended for anyone working in, researching in, or simply interested in shipping and the maritime domain and the evolution of autonomous shipping. The target audience includes regulators, educators, researchers, engineers, and manufacturers. The Open Access version of this book, available at <http://www.taylorfrancis.com>, has been made available under a Creative Commons Attribution-Non Commercial-No Derivatives (CC-BY-NC-ND) 4.0 license

Handbook of Power Electronics in Autonomous and Electric Vehicles

Handbook of Power Electronics in Autonomous and Electric Vehicles provides advanced knowledge on autonomous systems, electric propulsion in electric vehicles, radars and sensors for autonomous systems, and relevant aspects of energy storage and battery charging. The work is designed to provide clear technical presentation with a focus on commercial viability. It supports any and all aspects of a project requiring specialist design, analysis, installation, commissioning and maintenance services. With this book in hand, engineers will be able to execute design, analysis and evaluation of assigned projects using sound engineering principles and commercial requirements, policies, and product and program requirements. - Presents core power systems and engineering applications relevant to autonomous and electric vehicles in characteristic depth and technical presentation - Offers practical support and guidance with detailed examples and applications for laboratory vehicular test plans and automotive field experimentation - Includes modern technical coverage of emergent fields, including sensors and radars, battery charging and monitoring, and vehicle cybersecurity

Autonomous and Connected Vehicles

AUTONOMOUS AND CONNECTED VEHICLES Discover the latest developments in autonomous vehicles and what the future holds for this exciting technology In *Autonomous and Connected Vehicles*, networking experts Dominique Paret and Hassina Rebaine deliver a robust exploration of the major technological changes taking place in the field, and describe the different levels of autonomy possible with current technologies and the legal and regulatory contexts in which new autonomous vehicles will circulate. The book also includes discussions of the sensors, including infrared, ultrasound, cameras, lidar, and radar, used by modern autonomous vehicles. Readers will enjoy the intuitive descriptions of Advanced Driver Assistance Systems (ADAS), network architectures (CAN-FD, FlexRay, and Backbone Ethernet), and software that power current and future autonomous vehicles. The authors also discuss how ADAS can be fused with data flowing over newer and faster network architectures and artificial intelligence to create greater levels of autonomy. The book also includes: A thorough introduction to the buzz and hype surrounding autonomous and connected vehicles, including a brief history of the autonomous vehicle Comprehensive explorations of common issues affecting autonomous and connected vehicles, including regulatory guidelines, legislation, relevant norms and standards, and insurance issues Practical discussions of autonomous vehicle sensors, from DAS to ADAS and HADAS, and VA L3 to L5 In-depth examinations of networks and architecture, including discussions of data fusion, artificial intelligence, and hardware architecture in vehicles Perfect for graduate and undergraduate students in programs dealing with the intersection of wireless communication technologies and vehicles, *Autonomous and Connected Vehicles* is also a must-read reference for industry professionals and researchers seeking a one-stop reference for the latest developments in vehicle communications technology.

Autonomous Vehicles, Volume 1

AUTONOMOUS VEHICLES Addressing the current challenges, approaches and applications relating to autonomous vehicles, this groundbreaking new volume presents the research and techniques in this growing

area, using Internet of Things (IoT), Machine Learning (ML), Deep Learning, and Artificial Intelligence (AI). This book provides and addresses the current challenges, approaches, and applications relating to autonomous vehicles, using Internet of Things (IoT), machine learning, deep learning, and Artificial Intelligence (AI) techniques. Several self-driving or autonomous (“driverless”) cars, trucks, and drones incorporate a variety of IoT devices and sensing technologies such as sensors, gyroscopes, cloud computing, and fog layer, allowing the vehicles to sense, process, and maintain massive amounts of data on traffic, routes, suitable times to travel, potholes, sharp turns, and robots for pipe inspection in the construction and mining industries. Few books are available on the practical applications of unmanned aerial vehicles (UAVs) and autonomous vehicles from a multidisciplinary approach. Further, the available books only cover a few applications and designs in a very limited scope. This new, groundbreaking volume covers real-life applications, business modeling, issues, and solutions that the engineer or industry professional faces every day that can be transformed using intelligent systems design of autonomous systems. Whether for the student, veteran engineer, or another industry professional, this book, and its companion volume, are must-haves for any library.

Distributed Autonomous Robotic Systems 2

Great interest is now focused on distributed autonomous robotic systems (DARS) as a new strategy for the realization of flexible, robust, and intelligent robots. Inspired by autonomous, decentralized, and self-organizing biological systems, the field of DARS encompasses broad interdisciplinary technologies related not only to robotics and computer engineering but also to biology and psychology. The rapidly growing interest in this new area of research was manifest in the first volume of Distributed Autonomous Robotic Systems, published in 1994. This second volume in the series presents the most recent work by eminent researchers and includes such topics as multirobot control, distributed robotic systems design, self-organizing systems, and sensing and navigation for cooperative robots. Distributed Autonomous Robotic Systems 2 is a valuable source for those whose work involves robotics and will be of great interest to those in the fields of artificial intelligence, self-organizing systems, artificial life, and computer science.

Lawfully Using Autonomous Weapon Technologies

This monograph provides a practical and operational perspective to the question of how to lawfully employ autonomous weapon systems (AWS) from the point-of-view of the technology's end-users: field commanders. While there is international consensus that targeting rules such as proportionality and precautions must be respected when using AWS, there is legal and practical ambiguity as to how to translate this normative commitment into practice. How are commanders in the field, when guns are already blazing, expected to exercise command-and-control when ordering AWS-attacks, and ensure that their targeting obligations remain fulfilled? The book discusses how commanders can use existing targeting frameworks to ensure that their use of AWS remains in compliance with the rules governing the conduct of hostilities. It invites the reader to step into the shoes of the military commander with all the operational pressure and uncertainty inherent to this position, and explores amongst others: - How to maintain control of AWS throughout a targeting cycle; - How to make informed and reasoned deployment decisions by analysing information related to the technical parameters of the AWS, the characteristics of the operational environment, and enemy countermeasures; - Under which circumstances AWS may not be used under targeting rules, such as indiscriminate attack, proportionality and the duty to cancel/suspend; - What extra precautionary measures unique to AWS technology can and should be employed; - When it is militarily desirable to employ AWS over other alternatives; and - Under what circumstances criminal liability may be attributed for AWS-related harm. It offers both academic and practical outputs: new legal and doctrinal insights on the technology that is useful for future legal developments, and workable recommendations and efficient flowcharts that can be adopted by commanders, military organisations or policymakers to ensure IHL-compliant deployment of AWS. Dr. Jonathan Kwik is a researcher at the T.M.C. Asser Institute in The Hague specialised in artificial intelligence and targeting law, and is a member of the Board of Experts of the Asia-Pacific Journal of International Humanitarian Law.

Computing Systems for Autonomous Driving

This book on computing systems for autonomous driving takes a comprehensive look at the state-of-the-art computing technologies, including computing frameworks, algorithm deployment optimizations, systems runtime optimizations, dataset and benchmarking, simulators, hardware platforms, and smart infrastructures. The objectives of level 4 and level 5 autonomous driving require colossal improvement in the computing for this cyber-physical system. Beginning with a definition of computing systems for autonomous driving, this book introduces promising research topics and serves as a useful starting point for those interested in starting in the field. In addition to the current landscape, the authors examine the remaining open challenges to achieve L4/L5 autonomous driving. Computing Systems for Autonomous Driving provides a good introduction for researchers and prospective practitioners in the field. The book can also serve as a useful reference for university courses on autonomous vehicle technologies. This book on computing systems for autonomous driving takes a comprehensive look at the state-of-the-art computing technologies, including computing frameworks, algorithm deployment optimizations, systems runtime optimizations, dataset and benchmarking, simulators, hardware platforms, and smart infrastructures. The objectives of level 4 and level 5 autonomous driving require colossal improvement in the computing for this cyber-physical system. Beginning with a definition of computing systems for autonomous driving, this book introduces promising research topics and serves as a useful starting point for those interested in starting in the field. In addition to the current landscape, the authors examine the remaining open challenges to achieve L4/L5 autonomous driving. Computing Systems for Autonomous Driving provides a good introduction for researchers and prospective practitioners in the field. The book can also serve as a useful reference for university courses on autonomous vehicle technologies.

Maritime Autonomous Surface Ships (MASS) - Regulation, Technology, and Policy

This book covers MASS regulation, technology, and policy. MASS development began with the realization of the 4th industrial revolution technologies such as big data, AI, IoT, and communication, which were also linked to technological development in the maritime field. However, it is still unclear how MASS will operate. This book is divided into three parts: MASS regulation, technology, and policy, and explains each part in detail. Part I “MASS regulation and safety” deals with IMO works for MASS, including IMO MASS RSE results which has been finished in 2021. In addition, the United Nations Convention on the Law of the Sea (UNCLOS), one of the most important international conventions to be considered for MASS operation, will be dealt with and various safety considerations will be explained in detail. Through this, this book explains in detail the regulatory considerations and safety considerations for MASS. In particular, the gaps and themes identified in IMO MASS RSE and the priority discussion needs are explained, and based on this, the development of a goal-based non-mandatory MASS code currently in progress is discussed. UNCLOS is a convention like the blueprint of the IMO Conventions, and it is very important to understand and meet the requirements of UNCLOS for the operation of MASS. Therefore, this book provides a detailed explanation of the application of UNCLOS. In particular, UNCLOS Article 94 would be a very important consideration. Also, this book covers COLREGs and technologies for MASS operations.

Civil Regulation of Autonomous Unmanned Aircraft Systems in Europe

This is an open access title available under the terms of a CC BY-NC-ND 4.0 License. It is free to read, download and share on Elgaronline, thanks to generous funding support from the European Union's Horizon 2020 research and innovation programme. This comprehensive book presents a unique and in depth overview of the regulatory frameworks governing Unmanned Aircraft Systems (UAS) across 11 European jurisdictions. It emphasises the complex and evolving nature of aviation law as it is applied to UAS technology and demonstrates the need for a more cohesive legal framework in this sector.

Unsettled Domains Concerning Autonomous System Validation and Verification Processes

The Federal Aviation Administration (FAA) and the Department of Transportation's (DOT's) National Highway Traffic Safety Administration (NHTSA) face similar challenges regarding the regulation of autonomous systems powered by artificial intelligence (AI) algorithms that replace the human factor in the decision-making process. Validation and verification (V&V) processes contribute to implementation of correct system requirements and the development life cycle - starting with the definition of regulatory, marketing, operational, performance, and safety requirements. The V&V process is one of the steps of a development life cycle starting with the definition of regulatory, marketing, operational, performance, and safety requirements. They define what a product is, and they flow down into lower level requirements defining control architectures, hardware, and software. The industry is attempting to define regulatory requirements and a framework to gain safety clearance of such products. This report suggests a regulatory text and a safety and V&V approach from an aerospace engineering perspective assessing the replacement of the human driver from the decision-making role by a computational system. It also suggests an approach where aerospace guidelines can be used alongside the International Organization for Standardization (ISO) standard ISO 26262 in order to define a viable and valuable framework for autonomous systems safety clearance (or certification). NOTE: SAE EDGE™ Research Reports are intended to identify and illuminate key issues in emerging, but still unsettled, technologies of interest to the mobility industry. The goal of SAE EDGE™ Research Reports is to stimulate discussion and work in the hope of promoting and speeding resolution of identified issues. SAE EDGE™ Research Reports are not intended to resolve the issues they identify or close any topic to further scrutiny. Click here to access the full SAE EDGETM Research Report portfolio. <https://doi.org/10.4271/EPR2019012>

Autonomous Ships and the Law

Interest in autonomous ships has grown exponentially over the past few years. Whereas a few years ago, the prospect of unmanned and autonomous vessels sailing on the seas was considered unrealistic, the debate now centers on when and in what format and pace the development will take place. Law has a key role to play in this development and legal obstacles are often singled out as principal barriers to the rapid introduction of new technologies in shipping. Within a few years, autonomous ships have turned from a non-issue to one of the main regulatory topics being addressed by the International Maritime Organization. However, the regulatory discussion is still in its infancy, and while many new questions have been raised, few answers have been provided to them to date. Increased automation of tasks that have traditionally been undertaken by ships' crews raises interesting legal questions across the whole spectrum of maritime law. The first of its kind, this book explores the issue of autonomous ships from a wide range of legal perspectives, including both private law and public law at international and national level, making available cutting-edge research which will be of significant interest to researchers in maritime law. Chapter 3 of this book is freely available as a downloadable Open Access PDF at <http://www.taylorfrancis.com> under a Creative Commons Attribution-Non Commercial (CC-BY-NC) 4.0 license.

Cost Engineering and Pricing in Autonomous Manufacturing Systems

The book focuses on analyzing and proposing costing and pricing models to be used in autonomous manufacturing systems with respect to different effective parameters and factors in such a high tech environment within some applied cases.

Maritime Autonomous Vehicles and International Law

Maritime autonomous vehicles (MAVs) have the potential to radically alter all uses of maritime space, with technology progressing faster than the law. This book explores the current international legal framework and the options available to regulate maritime security in the face of emerging technologies. MAVs are starting to

play a role not only in policing and military security but also for the perpetration of maritime crimes. Through discussing the existing international legal framework for combating maritime security threats, the book will consider the use of MAVs by states for various security purposes and the potential dangers of MAVs in the hands of non-state actors. As the intersection of maritime technology with international maritime security law is crucial to a safe future for all, this timely book makes essential suggestions to adapt existing legal frameworks to match emerging technologies. Addressing critical questions such as who exercises jurisdiction when ships are remotely controlled, how jamming technology may be lawfully deployed and what force may be permissible during maritime law enforcement, this book identifies a diversity of current legal gaps and problems and makes suggestions as to how to rectify them. This book will be of interest to students and scholars in the field of the law of the sea, maritime security and emerging technologies.

Human-Like Decision Making and Control for Autonomous Driving

This book details cutting-edge research into human-like driving technology, utilising game theory to better suit a human and machine hybrid driving environment. Covering feature identification and modelling of human driving behaviours, the book explains how to design an algorithm for decision making and control of autonomous vehicles in complex scenarios. Beginning with a review of current research in the field, the book uses this as a springboard from which to present a new theory of human-like driving framework for autonomous vehicles. Chapters cover system models of decision making and control, driving safety, riding comfort and travel efficiency. Throughout the book, game theory is applied to human-like decision making, enabling the autonomous vehicle and the human driver interaction to be modelled using noncooperative game theory approach. It also uses game theory to model collaborative decision making between connected autonomous vehicles. This framework enables human-like decision making and control of autonomous vehicles, which leads to safer and more efficient driving in complicated traffic scenarios. The book will be of interest to students and professionals alike, in the field of automotive engineering, computer engineering and control engineering.

Sustainable Power, Autonomous Ships, and Cleaner Energy for Future Shipping

This exciting new book highlights and discusses new concepts for enhanced efficiency of ships and how they are operated, primarily resting on reducing the environmental footprints and operational expenses. An overview of technological and regulatory developments and drivers for the challenges described above is provided. Readers learn about sustainable energies and power for propulsion, particularly maritime electrification. The book includes shore-based initiatives on greenhouse gas reduction in shipping. Status and current practices for propulsion arrangements using renewable energy technologies are presented with examples on ships representing several categories of energies and power. Energy solutions that enable future digital and automated concepts for safe, secure, and cost-effective sustainable shipping are discussed, as well as the concept of autonomous ships as part of maritime electrification and all the possibilities. The development of renewable energies and the concept of autonomous ships provide glimpses for the development of future sustainable maritime transport solutions. Lessons learned and existing knowledge are important elements for successful transmission towards future concepts for safe, secure, and efficient maritime environmentally friendly and low-cost solutions to our sustainable power and energy challenges that lie ahead. The book discusses the work ahead and provides future thoughts on this issue.

Human Performance in Automated and Autonomous Systems

This book examines recent advances in theories, models, and methods relevant to automated and autonomous systems. The following chapters provide perspectives on modern autonomous systems, such as self-driving cars and unmanned aerial systems, directly from the professionals working with and studying them. Current theories surrounding topics such as vigilance, trust, and fatigue are examined throughout as predictors of human performance in the operation of automated systems. The challenges related to attention and effort in

autonomous vehicles described within give credence to still-developing methods of training and selecting operators of such unmanned systems. The book further recognizes the need for human-centered approaches to design; a carefully crafted automated technology that places the \"human user\" in the center of that design process. Features Combines scientific theories with real-world applications where automated technologies are implemented Disseminates new understanding as to how automation is now transitioning to autonomy Highlights the role of individual and team characteristics in the piloting of unmanned systems and how models of human performance are applied in system design Discusses methods for selecting and training individuals to succeed in an age of increasingly complex human-machine systems Provides explicit benchmark comparisons of progress across the last few decades, and identifies future prognostications and the constraints that impinge upon these lines of progress Human Performance in Automated and Autonomous Systems: Current Theory and Methods illustrates the modern scientific theories and methods to be applied in real-world automated technologies.

Autonomous Nuclear Power Plants with Artificial Intelligence

This book introduces novel approaches and practical examples of autonomous nuclear power plants that minimize operator intervention. Autonomous nuclear power plants with artificial intelligence presents a framework to enable nuclear power plants to autonomously operate and introduces artificial intelligence (AI) techniques to implement its functions. Although nuclear power plants are already highly automated to reduce human errors and guarantee the reliability of system operations, the term “autonomous” is still not popular because AI techniques are regarded as less proven technologies. However, the use of AI techniques and the autonomous operation seems unavoidable because of their great advantages, especially, in advanced reactors and small modular reactors. The book includes the following topics: Monitoring, diagnosis, and prediction. Intelligent control. Operator support systems. Operator-autonomous system interaction. Integration into the autonomous operation system. This book will provides useful information for researchers and students who are interested in applying AI techniques in the fields of nuclear as well as other industries. This book covers broad practical applications of AI techniques from the classical fault diagnosis to more recent autonomous control. In addition, specific techniques and modelling examples are expected to be very informative to the beginners in the AI studies.

Attractors for infinite-dimensional non-autonomous dynamical systems

The book treats the theory of attractors for non-autonomous dynamical systems. The aim of the book is to give a coherent account of the current state of the theory, using the framework of processes to impose the minimum of restrictions on the nature of the non-autonomous dependence. The book is intended as an up-to-date summary of the field, but much of it will be accessible to beginning graduate students. Clear indications will be given as to which material is fundamental and which is more advanced, so that those new to the area can quickly obtain an overview, while those already involved can pursue the topics we cover more deeply.

Intelligent Cyber-Physical Systems for Autonomous Transportation

This book provides comprehensive discussion on key topics related to the usage and deployment of AI in urban transportation systems including drones. The book presents intelligent solutions to overcome the challenges of static approaches in the transportation sector to make them intelligent, adaptive, agile, and flexible. The book showcases different AI-deployment models, algorithms, and implementations related to intelligent cyber physical systems (CPS) along with their pros and cons. Even more, this book provides deep insights into the CPS specifically about the layered architecture and different planes, interfaces, and programmable network operations. The deployment models for AI-based CPS are also included with an aim towards the design of interoperable and intelligent CPS architectures by researchers in future. The authors present hands on practical implementations, deployment scenarios, and use cases related to different transportation scenarios. In the end, the design and research challenges, open issues, and future research directions are provided.

The Disruptive Impact of Lethal Autonomous Weapons Systems Diffusion

Challenging the focus on great powers in the international debate, this book explores how rising middle power states are engaging with emerging major military innovations and analyses how this will affect the stability and security of the Indo Pacific. Presenting a data-based analysis of how middle power actors in the Indo-Pacific are responding to the emergence of military Artificial Intelligence and Killer Robots, the book asserts that continuing to exclude non-great power actors from our thinking in this field enables the dangerous diffusion of Lethal Autonomous Weapon Systems (LAWS) to smaller states and terrorist groups, and demonstrates the disruptive effects of these military innovations on the balance of power in the Indo-Pacific. Offering a detailed analysis of the resource capacities of China, United States, Singapore and Indonesia, it shows how major military innovation acts as a circuit breaker between competitor states disrupting the conventional superiority of the dominant hegemonic state and giving a successful adopter a distinct advantage over their opponent. This book will appeal to researchers, end-users in the military and law enforcement communities, and policymakers. It will also be a valuable resource for researchers interested in strategic stability for the broader Asia-Pacific and the role of middle power states in hegemonic power transition and conflict.

Army of None: Autonomous Weapons and the Future of War

Winner of the 2019 William E. Colby Award —"The book I had been waiting for. I can't recommend it highly enough." —Bill Gates The era of autonomous weapons has arrived. Today around the globe, at least thirty nations have weapons that can search for and destroy enemy targets all on their own. Paul Scharre, a leading expert in next-generation warfare, describes these and other high tech weapons systems—from Israel's Harpy drone to the American submarine-hunting robot ship Sea Hunter—and examines the legal and ethical issues surrounding their use. "A smart primer to what's to come in warfare" (Bruce Schneier), *Army of None* engages military history, global policy, and cutting-edge science to explore the implications of giving weapons the freedom to make life and death decisions. A former soldier himself, Scharre argues that we must embrace technology where it can make war more precise and humane, but when the choice is life or death, there is no replacement for the human heart.

Critical Analysis of Prototype Autonomous Vehicle Crash Rates

Will Automated Vehicles be Safer than Conventional Vehicles? One of the critically important questions that has emerged about advanced technologies in transportation is how to test the actual effects of these advanced systems on safety, particularly how to evaluate the safety of highly automated driving systems. Richard Young's *Critical Analysis of Prototype Autonomous Vehicle Crash Rates* does a deep dive into these questions by reviewing and then critically analyzing the first six scientific studies of AV crash rates.

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